# Generalized Geometry, an introduction Assignment 1 

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Problem 1. Consider the vector space $\mathbb{R}^{4}$ with the symplectic form

$$
\omega\left(\left(x_{1}, y_{1}, x_{2}, y_{2}\right),\left(x_{1}^{\prime}, y_{1}^{\prime}, x_{2}^{\prime}, y_{2}^{\prime}\right)\right)=\sum_{i=1}^{2}\left(x_{i} y_{i}^{\prime}-y_{i} x_{i}^{\prime}\right)
$$

- Find a subspace $U$ such that $U=U^{\omega}$.
- Find a plane $U$, i.e., a subspace isomorphic to $\mathbb{R}^{2}$, such that $U+U^{\omega}=\mathbb{R}^{4}$.

Problem 2. A subspace $U$ of a symplectic vector space $(V, \omega)$ such that $U^{\omega} \subseteq U$ is called a coisotropic subspace. Prove that the quotient $U / U^{\omega}$ naturally inherits a symplectic structure. This is called the coisotropic reduction.

Problem 3. Given a symplectic form, we have an isomorphism $V \rightarrow V^{*}$. We invert this isomorphism to get a map $V^{*} \rightarrow V$, which we can see as a map

$$
\pi: V^{*} \times V^{*} \rightarrow k
$$

Prove that the map $\pi$ is bilinear, non-degenerate and skew-symmetric.

Problem 4. Consider a real vector space with a linear complex structure $(V, J)$ and its complexification $V_{\mathbb{C}}$. Prove that $i J=J i$. When does the map

$$
a i+b J
$$

for $a, b \in \mathbb{R}$, define a linear complex structure on $V_{\mathbb{C}}$, seen as a real vector space?

Problem 5. Consider a real vector space with a linear complex structure $(V, J)$. Prove that the map

$$
J^{*}: V^{*} \rightarrow V^{*},
$$

given by

$$
J^{*} \alpha(v)=\alpha(J v)
$$

for $\alpha \in V^{*}$ and $v \in V$, defines a linear complex structure on $V^{*}$. Given a basis $\left(v_{i}\right)$ with dual basis $\left(v^{i}\right)$, prove that

$$
J^{*} v^{i}=-\left(J v_{i}\right)^{*}
$$

Problem 6. The invertible linear transformations of $\mathbb{R}^{n}$ are called the general linear group and denoted by $\mathrm{GL}(n, \mathbb{R})$. If they moreover preserve the euclidean metric, we have the orthogonal group $\mathrm{O}(n, \mathbb{R})$. For a vector space $V$, we write $\mathrm{GL}(V)$ and $\mathrm{O}(V, g)$ when $V$ comes with a linear riemannian metric $g$.

- Show that a basis $\left\{v_{i}\right\}$ determines a linear riemannian metric by $g\left(v_{i}, v_{j}\right)=$ $\delta_{i j}$, and hence any vector space admits a linear riemannian metric.
-     * Can two different bases determine the same riemannian metric? If so, describe the space of bases determining the same riemannian metric.
-     * Conversely, given a linear riemannian metric, how can you describe the space of all metrics?

Problem 7. * Describe the space of linear complex structures on a given even-dimensional real vector space.

